Hamed Alimohammadzadeh

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EDUCATION

University of Southern California Doctor of Philosophy (Ph.D.) – Computer Science

• Advised by Prof. Shahram Ghandeharizadeh

University of Southern California

Master of Science (MS) - Computer Science

Sharif University of Technology

Bachelor of Science (BS) - Computer Engineering

• Thesis: Multi-Modal Object Detection by Improving Neural Network Learning. Advised by Prof. Shohreh Kasaei.

RESEARCH INTERESTS

Swarm Robotics: coordinate swarms of flying robots to render 3D point clouds.Computer Vision: use vision to determine the position of robots in swarms for localization.Human-Computer Interaction: create immersive multimedia displays using swarms of UAVs with haptic feedback.

SKILLS

Programming Languages: Python, C/C++, JavaScript, MATLAB, Java, C# Software & Tools: OpenCV, Unity, Blender, Pandas, PyTorch, scikit, OpenGL/WebGL, ROS Additional Skills: Graphic Design (Photoshop, Illustrator), Web Development (Vue, TypeScript, React, Express, MongoDB)

PUBLICATIONS

- Swarical: An Integrated Hierarchical Approach to Localizing Flying Light Specks H. Alimohammadzadeh, S. Ghandeharizadeh.
 In ACM Multimedia, Melbourne, Australia, 28 October - 1 November 2024.
- [2] Reliability Groups with Standby Flying Light Specks
 H. Alimohammadzadeh, S. Zhu, S. Ghandeharizadeh
 In ACM SIGMM Conference on Multimedia Systems, Bari, Italy, April 15-18, 2024.
- [3] Force-Feedback Through Touch-based Interactions With A Nanocopter
 Y. Chen, H. Alimohammadzadeh, S. Ghandeharizadeh, H. Culbertson
 In 2024 IEEE Haptics Symposium (HAPTICS), Long Beach, USA, April 7-10, 2024.
- [4] SwarMer: A Decentralized Localization Framework for Flying Light Specks
 H. Alimohammadzadeh, S. Ghandeharizadeh
 In the First International Conference on Holodecks, Los Angeles, USA, December 15, 2023.
- [5] A Conceptual Model of Intelligent Multimedia Data Rendered using Flying Light Specks N. Yazdani, H. Alimohammadzadeh, S. Ghandeharizadeh In the First International Conference on Holodecks Los Angeles, USA, December 15, 2023.

August 2022 - Expected 05/26

August 2022 - May 2024

September 2017 - July 2022

- [6] Towards a Stable 3D Physical Human-Drone Interaction Y. Chen, H. Alimohammadzadeh, S. Ghandeharizadeh, H. Culbertson In First International Conference on Holodecks, Los Angeles, USA, December 15, 2023.
- [7] Towards Enabling Complex Touch-based Human-Drone Interaction Y. Chen, H. Alimohammadzadeh, S. Ghandeharizadeh, H. Culbertson In Workshop on Human Multi-Robot Interaction, IROS, Detroit, USA, October 1, 2023.
- [8] An Evaluation of Decentralized Group Formation Techniques for Flying Light Specks H. Alimohammadzadeh, H. Culbertson, and S. Ghandeharizadeh In ACM Multimedia Asia, Taipei, Taiwan, December 6-8, 2023.
- [9] An Evaluation of Three Distance Measurement Technologies for Flying Light Specks T. Phan, H. Alimohammadzadeh, H. Culbertson, and S. Ghandeharizadeh In International Conference on Intelligent Metaverse Technologies and Applications, Tartu, Estonia, September 18-20, 2023.
- [10] Dronevision: An Experimental 3D Testbed for Flying Light Specks H. Alimohammadzadeh, R. Bernard, Y. Chen, T. Phan, P. Singh, S. Zhu, H. Culbertson, and S. Ghandeharizadeh In the First International Conference on Holodecks, October 1, 2023.
- [11] Modeling Illumination Data with Flying Light Specks H. Alimohammadzadeh, D. Mehraban, and S. Ghandeharizadeh In Proceedings of the 14th Conference on ACM Multimedia Systems, Vancouver, Canada, June 7-10, 2023.

EXPERIENCE

Flying Light Specks Lab (FLS Lab), University of Southern California Research Assistant - PI: Prof. Shahram Ghandeharizadeh

- Research technologies to realize 3D multimedia displays using miniature drones, including the design of fast localization algorithms, group formation techniques, and haptic interactions.
- Design decentralized localization algorithms for swarms of drones to illuminate 3D point clouds efficiently.
- Create multi-process and multi-threaded emulators for decentralized algorithms with 1000+ communicating nodes on AWS and Cloudlab using Python.
- Hands-on experience with Crazyflies to evaluate downwash effects and haptic interactions with multiple drones.
- Implement real-time position estimation techniques using Raspberry Pi and camera modules for drones.

Image Processing Lab (IPL), Sharif University of Technology

Research Assistant - PI: Prof. Shohreh Kasaei

• Implemented a domain generalization algorithm for multi-domain mitosis figure detection using FastAI and RetinaNet in Python.

Sotoon Cloud Services

Front-End Engineer

- Developed and maintained a web application for voice and image annotation using Vue with 120+ customers, doubling annotation speed.
- Designed and developed accessible components for a UI framework using Vue 3, TypeScript, and Tailwind.
- Designed interview tasks and interviewed 60+ applicants for front-end engineering positions.
- Mentored two front-end engineers in their onboarding process.

June 2020 - August 2022

September 2021 - July 2022

August 2022 - Present

LEADERSHIP

Technical Lead, Sharif AI Challenge 2020, Sharif University of Technology November 2019 - April 2020 • Led four technical teams, including game designers, web developers, and software engineers, for designing and implementing a competition in AI held by SSC where 300+ AI agents compete against each other to win a tournament. SERVICE 1. Communication chair and program committee member of the 2nd International Conference on Holodecks 2024 2. Reviewed 3 technical papers as an invited reviewer for ACM-Multimedia'24 2024 3. Communication chair and program committee member of the First International Conference on Holodecks 2023 4. Reviewed 3 technical papers as an invited reviewer for ACM-Multimedia'23 2023 **MENTORSHIP** • Kariena Panpaliya (undergraduate, USC CURVE program) 2024 Xuanyu Pan (undergraduate, USC CURVE program) 2024 ٠ • Wallace Browning (undergraduate, USC) 2024 MEDIA • Our work for the Holodecks conference is featured in the USC Viterbi School of Engineering news article 2024 AWARDS 2022 • USC Graduate School Fellowship for 1 year of the PhD program RoboCup Iran Open 2nd rank in Junior Rescue-A League 2015 • RoboCup Iran Open 1st in Junior Rescue-A super-team competition 2015 PROJECTS • Created a system for bidirectional teleoperation of a UAV with haptic feedback for obstacle avoidance, using 3D Systems Touch Haptic Device and Crazyflies. 2023 Developed a minimalistic social media platform using microservices architecture, utilizing Express.js for backend services, Vue.js for the frontend, NGINX for load balancing, and Docker for containerization. 2021

• Organized 10+ competitions, workshops, and extracurricular events at the Department of Computer Engineering

July 2020 - July 2021

Board Chair, Students' Scientific Chapter (SSC), Sharif University of Technology

at Sharif University of Technology, attracting 2000+ participants country-wide.